

EXPLORER 700

Expansion board

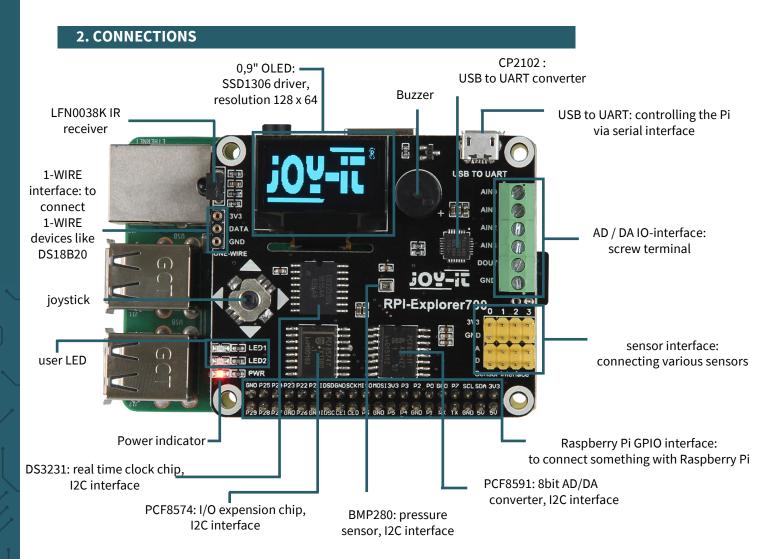


1. GENERAL INFORMATION

Dear customer,

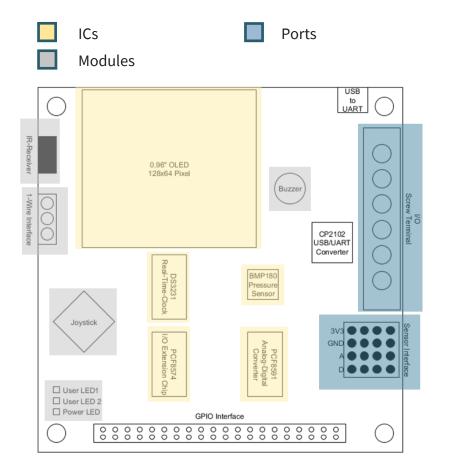
Thank you for purchasing our product. In the following, we will show you which things should be noted during the use.

Should you encounter any unexpected problems, do not hesitate to contact us.

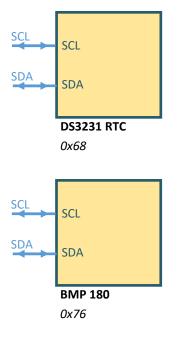


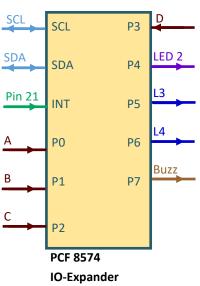
Schematic overview

All pins listed here refer to the GPIO/BCM pins of the Raspberry Pi.

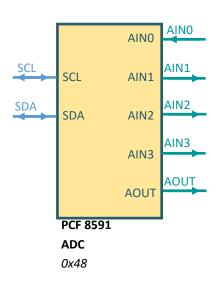


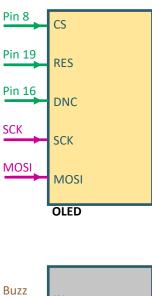
3V3	• •	
SDA	•	
SCL	\circ	GND
Pin 4	•••	
GND	• •	
	$\bullet \bullet$	Pin 18
	\bullet	GND
	•••	
3V3	•••	
MOSI		GND
SCK		
		Pin 8
GND		
Pin 5	$\bullet \bullet$	GND
Pin 6	•••	Pin 12
Pin 13	\bullet	GND
Pin 19	•••	Pin 16
Pin 26	\circ	Pin 20
GND		Pin 21

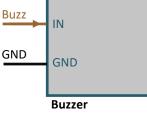




0x20

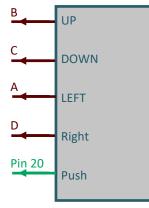






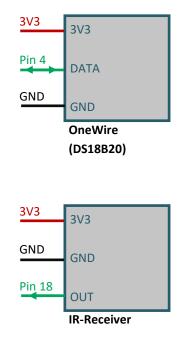


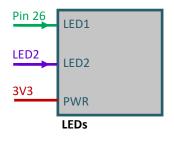
Backside of Explorer 700

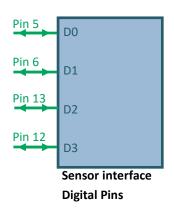


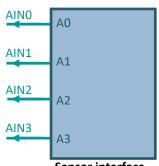
Joystick

	AIN0	AIN3	AIN3
AIN1	AIN1	DOUT	AOUT
AIN2	AIN2	GND	GND
-	Screw to		





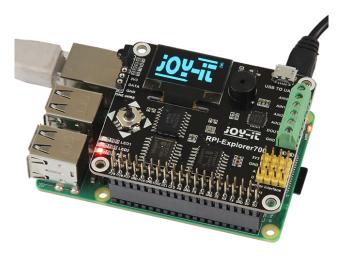




Sensor interface Analog Pins

3. CONNECTING THE EXPANSIONBOARD

The Explorer 700 expansion board supports the Raspberry Pi A+, B+, 2, 3 Model B and 4. Before you can perform the code examples, you should ensure that the Explorer 700 is connected to your Raspberry Pi and it is provided with power.



4. AVAILABLE DOWNLOAD

We provide you with a pre installed image, which saves you the trouble of installing and setting up libraries. You can download the image <u>here</u>.

To install the image on your microSD card, you can use <u>Win32DiskImager</u>. Here you select the microSD card to write to and the downloaded image. Now click on *Write* to write on this SD card.

If you are not using our image, you can download our sample codes <u>here</u>, which will help you to access these samples. But then please note the following two chapters.

These chapters can be skipped when using our image.

5. INSTALLATION OF THE LIBRARIES

To use API examples which we offer, certain libraries are required which should be installed manually, if you are not using our image. Python libraries for Raspbian (includes Raspberry Pi, GPIO and spidev installation packages. See: <u>https://pypi.python.org/pypi/RPi.GPIO</u> <u>https://pypi.python.org/pypi/spidev</u>) You get them with the command *wget*.

Please note that the Raspberry Pi must be connected with the internet if you want to us this command to install the library. Beforehand, you can use the following command to update your software to the latest.

sudo apt-get update
sudo apt-get upgrade

Enter now the following command to install the Python-dev package.

sudo apt-get install python3-dev

Enter the following commands to install the smbus and smbus2 library (I2C interfaces functions):

```
sudo apt-get install python3-smbus
sudo pip3 install smbus2
```

Enter the following command to install the serial library which includes the UART interface functions.

sudo apt-get install python3-serial

For our code examples, the libraries **<u>RPi.GPIO</u>** and <u>**spidev**</u> are mandatory.

You can install the RPi.GPIO library with the following command:

```
sudo apt-get install python3-rpi.gpio
```

The spidev library with this command:

```
sudo pip3 install spidev
```

To use the OLED, you must install this library :

sudo apt-get install python3-pil

Furthermore, for the BMP2802 you need libraries from Adafruit <u>CircuitPython_BMP280</u> and <u>CircuitPython_Bundle</u>, which are both published under the MIT license (<u>BMP280</u> and <u>Bundle</u>). You install them as follows:

```
sudo apt-get install git
git clone https://github.com/adafruit/Adafruit_CircuitPython_BMP280.git
sudo pip3 install adafruit-circuitpython-bmp280
git clone https://github.com/adafruit/Adafruit_CircuitPython_Bundle.git
sudo pip3 install adafruit-circuitpython-lis3dh
```

To install the ADC library, enter the following commands:

```
git clone https://github.com/joy-it/PCF8591-python3-lib.git
cd ~/PCF8591-python3-lib/
sudo python3 setup.py install
```

6. CONFIGURATION OF THE INTERFACES

Before running the API codes we provide, you should activate the appropriate drivers for the interfaces.

Activation of the I2C-function

Enter the following command to configure your Raspberry Pi board.

sudo raspi-config

Choose in *Interfacing Options* \rightarrow *I2C* \rightarrow *Yes* to start the core driver of I2C. Afterwards, you should adjust the configuration file. To open the configuration file, enter the following:

sudo nano /etc/modules

Add the following two lines at the end of the configuration file:

i2c-bcm2708 i2c-dev

Press the key combination *CTRL + X* to leave the settings and press *Y* to save them.

Activation of the serial functions

The serial port of the Raspberry Pi is set on the debugging via console mode by default. If you want to use the serial port as a normal IO, you have to adjust the configuration of the Raspberry Pi. If the debugging via console function is deactivated, you can not access the Raspberry Pi board via the serial port. If you want to control the Raspberry, you must activate the debugging of the serial port via the console function again.

sudo raspi-config

Choose in *Interfacing Options* \rightarrow *Serial*. Through selecting the option *No* the debugging via the console function will be deactivated. Afterwards, the serial port can be used for the serial communication. With selecting the option *Yes* the debugging via console function can be activated again.

You also need to activate the 1-Wire interface. To do this, select *Interfacing Options* \rightarrow *1-Wire* and activate the function with *Yes*.

You should now restart the Raspberry Pi.

Note: The serial port of the Raspberry Pi 3B is not available because pin14 and 15 are connected with its own Blue-

tooth.

To still use the serial functions, you have to enable the SPI-function. For that, you open the terminal and enter the following command:

sudo raspi-config

Now you only have to choose in *Interfacing Options* \rightarrow *SPI* \rightarrow *Yes* to enable the SPI functions.

7. ANALOG DIGITAL CONVERTER EXAMPLES

The Explorerboard has 4 analog inputs which can be converted to digital signals by the ADC PCF8591.

To start the example program, enter the following commands:

cd ~/PCF8591-python3-lib/examples/ sudo python3 read.py

The board also has an analog output, which can be used to output an analog signal.

To start the example program, enter the following commands:

cd ~/PCF8591-python3-lib/examples/ sudo python3 write.py

8. CHANGING THE LED STATUS

The explorer board has LEDs which can be controlled by our code examples. LED1 can be used directly. To use this LED open the terminal and enter the following commands:

cd ~/Desktop/Explorer-700/LED1/
sudo python3 led.py

LED1 should now start blinking. Press the keys **CTRL + C** to exit this program. There is another code for LED1 which lets it pulsate.

sudo python3 pwm.py

Press the keys **CTRL + C** to exit happens.

The joystick has next to the press function the common directions of movement. Our code example shows when the press function is used.

Open the Linux console and enter the following commands:

```
cd ~/Desktop/Explorer-700/
sudo python3 press-joystick.py
```

By pressing the Joystick, the console will show the following:

JOYSTICK PRESSED JOYSTICK PRESSED JOYSTICK PRESSED

Press the keys **CTRL + C** to exit this program.

10. I/O-EXPANDER - PCF8574

The I/O Expander PCF8574 also controls the LED2, the buzzer and the joystick.

Open the console and enter the following commands:

cd ~/Desktop/Explorer-700/
sudo python3 led2.py

With this program, LED2 is blinking. Press the keys **CTRL + C** to exit the program.

sudo python3 joystick.py

This program combines the functions of the Explorerboard, which are controlled by the PCF8574. When the joystick is pressed in one direction, the buzzer sounds, LED2 lights up and the console outputs the direction in which the joystick is pressed.

up left down right

Press the keys **CTRL + C** to exit this program.

11. BAROMETER - BMP280

This sample code is based on two Adafruit libraries (**chapter 5**). This sensor can measure temperature and air pressure and can therefore also calculate the altitude.

Note that the temperature can be influenced by the heat of the Raspberry Pi.

In order to calculate a correct altitude, change the sea air pressure to the air pressure at the current location in the sample code.

cd ~/Desktop/Explorer-700/BMP280/ sudo python3 bmp280.py

Press the keys **CTRL + C** to exit this program.

12. REAL - TIME CLOCK - DS3231

You can terminate the connection to the RTC with the following command:

sudo i2cdetect -y 1

Now you should see an address with which you can control the RTC. With us it is 0x68. If this address is different, you must change it in the code example.

You can embed this RTC into your system as a real-time clock or use it only in a code. Please note that a real-time clock is only fully functional if a battery is installed in the corresponding battery holder.

Embedding in the system

First, you edit the *modules* file. You do this with the following command:

sudo nano /etc/modules

Add this line to the end of the file:

rtc-ds3231

You can save the file with **CTRL + O** and exit the editor with **CTRL + X**. Now you have to edit the *config.txt*. Open it with the following command:

sudo nano /boot/config.txt

There you add this line to the end of the file:

```
dt-overlay=i2c-rtc,ds3231
```

You can save the file again with **CTRL** + **O** and exit the editor **with CTRL** + **X**. Now, you have to install the driver of the RTC. The driver of DS1307 (another RTC) is also used by DS3231.

sudo modprobe rtc-ds1307

Now edit the following file to set the system time after a start to the time of the RTC:

sudo nano /etc/rc.local

Above the command *exit 0* add the following three lines:

echo ds3231 0x68 > /sys/class/i2c-adapter/i2c-1/new_device
hwclock --hctosys
date
exit 0

Close the file again with **CTRL + O** and **CTRL + X** and restart the Raspberry Pi. Now the time of the system after each restart is set by the RTC.

Note that a CR1220 battery must be inserted in the battery holder so that the real-time clock can maintain the correct time.

Afterwards, you can control the RTC as one of the system. Therefore, you can now use the following commands:

sudo hwclock -r

With this command the time of the RTC can be output.

sudo hwclock -w

This command adjusts the RTC to the time of the system.

<u>Use in code</u>

If you want to use your RTC in the code, you must uninstall the drivers of the RTC or do not embed the RTC in the system, because the driver of the RTC blocks it for further processes. You can uninstall the driver with:

sudo rmmod rtc-ds1307

You only need to execute this command if you have embedded the RTC in the system. You should then also remove the added lines in *rc.local* to avoid incorrect changes in the system.

In our code example we use the library <u>RTC_SDL_DS3231</u> published by <u>SwitchDoc Labs</u>.

To execute the code, you must go first into subfolder . You do this with the following command:

cd ~/Desktop/Explorer-700/RTC_SDL_DS3231

There you can execute our code, which maps the RTC to system time and sets the time and date every second. You can execute this code with the following command:

sudo python3 ds3231.py

Press the keys **CTRL + C** to exit this program.

13. TEMPERATURE SENSOR - DS18B20

The temperature sensor which is included in the scope of delievery, must be connected seperately and is not on the board. Thereby, you should note that the straight side of the sensor is showing to the display and the rounded side is pointing torwards the Raspberry Pis USB and ethernet ports.



For this example, open the console and enter the following command:

cd ~/Desktop/Explorer-700
sudo python3 ds18b20.py

The console will display the temperature in Celsius.

24.687 *C 24.750 *C 24.812 *C

Press the keys **CTRL + C** to exit this program.

14. IRM - INFRARED REFLECTING SENSOR

On the board is an infrared receiver which can convert infrared into electric signals. This signals include the infrared values which are issued by the console via this code example.

cd ~/Desktop/Explorer-700
sudo python3 irm.py

Therefore, an infrared remote controll is requiered, which is not included in the scope of delievery.

IRM test start: Get the key: 0x0c Get the key: 0x18cd Get the key: 0x5e

Press the keys **CTRL + C** to exit this program.

15. UART - TRANSMISSON OF SERIAL DATA

The serial interface of the Raspberry Pi is by default deactivated. For this program, you must enable this function so that the Raspberry Pi is not communicating via the serial port. Instead, other methods must be used to communicate with the Raspberry Pi.

To use this code example, you first have to change the serial function in the configuration of the Raspberry Pi.

For that, enter the following command into the console:

sudo raspi-config

Now navigate with the arrowkey to the option 5 Interfacing Options.



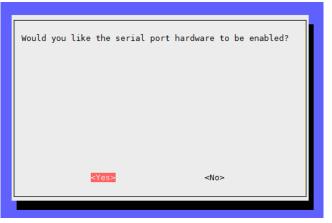
After that choose **Punkt P6 Serial**.

I	Raspberry Pi Software	e Configuration Tool (raspi-config)
P1 Camera P2 SSH P3 VNC P4 SPI P5 I2C P6 Serial P7 1-Wire P8 Remote		Enable/Disable connection to the Ra Enable/Disable remote command line Enable/Disable graphical remote acc Enable/Disable automatic loading of Enable/Disable automatic loading of Enable/Disable atomatic loading of Enable/Disable shell and kernel mes Enable/Disable one-wire interface Enable/Disable remote access to GPI
	<select></select>	<back></back>

Answer the question *Would you like a login shell to be accessible over serial?* with **No**.

Would you like serial?	e a login shell to be a	accessible over
	<yes></yes>	<no></no>

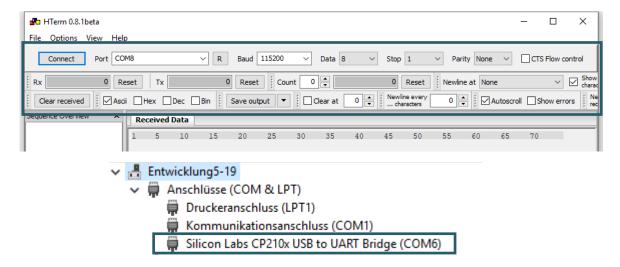
Answer the question *Would you like the serial port hardware to be enabled?* with **Yes**.



The USB to UART interface of your Raspberry Pi allows you to connect the Pi with your computer and to let them communicate without a connection with the internet.

In this example, we use HTerm. Download this program <u>here</u> and install it.

First of all, open HTerm and assume the settings like shown in the picture. Therefore, it is to note that you set the right baudrate (115200) and the right port. You should also note that your port could be different which you should ensure in the device manager.



Now you can click on Connect to establish a connection. As the next step, you have to start the code example on your Raspberry Pi. For that enter the following:

cd ~/Desktop/Explorer-700

sudo python3 uart.py

In HTerm you will see the following:

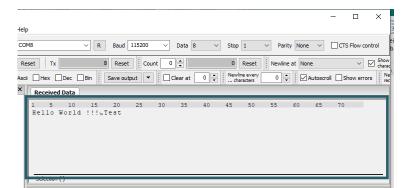
	Rec	eive	d Data													
	l Hel	5 10	10 World	15 !!! _∿	20	25	30	35	40	45	50	55	60	65	70	
L	Sele	ection	ı (-)													

Now you can send texts to your Raspberry Pi. The code examples allows that the Raspberry Pi will send all sent texts from your computer back to your computer.

You can enter these texts in the text field and send them with *ASend*.

Rec	ceive	d Data													
1	5	10	15	20	25	30	35	40	45	50	55	60	65	70	
Hel	110	World	!!! _{\0}												
Sel	ection	(-)													
nput	contro	ol													×
Inpu	it opti	ons													
C	ear tr	ansmitted	As	cii 🗌 H	lex 🗌 De	e 🗌 B	in Ser	nd on ent	er None	\sim	Sen	d file	DTR	RTS	
Туре	ASC	~	Test												ASend
ransr	mitted	data													×
1	5	10	15	20	25	30	35	40	45	50	55	60	65	70	75
					Histo	ory -/1/1	10	Conne	ct to CO	M8 (b:11	5200 d:8	s:1 p:No	ne)		

After that your computer will receive the following:



You can open the terminal console via the UART connection instead of an external display or via the internet. Therefore, you can use PuTTY, MobaXterm or others for the connection. For that, you have to change your settings again.

First, enter the following command into the console:

sudo raspi-config

Navigate now with the arrow key to the option **5 Interfacing Options.**

Raspberry Pi Softwar	e Configuration Tool (raspi-config)
1 Change User Password 2 Network Options 3 Boot Options 4 Localisation Options 5 Interfacing Options 6 Overclock 7 Advanced Options 8 Update 9 About raspi-config	Change password for the current use Configure network settings Configure options for start-up Set up language and regional settin Configure connections to peripheral Configure overclocking for your Pi Configure advanced settings Update this tool to the latest vers Information about this configuratio
<select></select>	<finish></finish>

Then choose point P6 Serial.

	Raspberry Pi Software	Configuration Tool (raspi-config)
P1 Camer P2 SSH P3 VNC P4 SPI P5 I2C P6 Seria P7 1-Wir P8 Remot	- L	Enable/Disable connection to the Ra Enable/Disable remote command line Enable/Disable graphical remote acc Enable/Disable automatic loading of Enable/Disable automatic loading of Enable/Disable shell and kernel mes Enable/Disable one-wire interface Enable/Disable remote access to GPI
	<select></select>	<back></back>

Answer the question *Would you like a login shell to be accessible over serial?* with **Yes**.

Would you serial?	like a login shel	l to be accessible over	
	<ja></ja>	<nein></nein>	

After a reboot, you can connect your Raspberry Pi with your computer. Now MobaXterm, which you can download <u>here</u> and establish a connection with the following setting:

ession setti	ngs													×
SSH	Telnet	8 Rsh	Xdmcp	TTP RDP	VNC	🜏 FTP	SFTP	,∳ Serial	9 File	Shell	(Browser	💉 Mosh	💖 Aws S3	
🖋 Ba	sic Serial Serial por		3 (Silicon	Labs CP	210x USB	to UART	Br v		Speed (bp	s) * <mark>115</mark>	200 🗸			
💉 Ad	vanced Ser	ial settin <u>c</u>	S 💕	Terminal s	settings	🔶 Во	okmark se	ttings						
	Serial (COM) session											×	ţ.	
					🕑 ОК		8	Cancel						

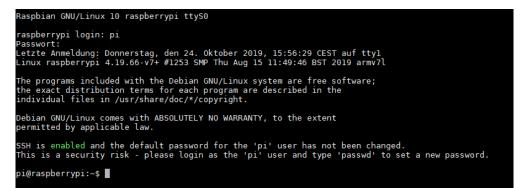
Therefore, you should note that you have to choose the connection type **Serial** and the right port (viewable in device manager) as well as to set the **baudrate** to **115200.**

Now, the console will be opened and you must log in on your Raspberry Pi. If you use our image, the user name is *pi* and the password is *raspberry*.

Attention, the keystrokes will not be shown if you enter your password.

Raspbian GNU/Linux 10 raspberrypi ttyS0 raspberrypi login: pi Passwort: 📕

After you logged in successfully, the console will open and you can use the terminal of the Raspberry Pi the same way as via SSH only without an internet connection.



16. OLED - DISPLAY

To execute these codes, make sure the **I2C** and **SPI** are activated. In **chapter 6** you can read how to activate both. The PIL library must also be installed. How to install it can be read in **chapter 5**.

Our code examples can generate different displays at the OLED. These differentiate in significant aspects from each other.

cd ~/Desktop/Explorer-700/OLED
sudo python3 dispchar.py

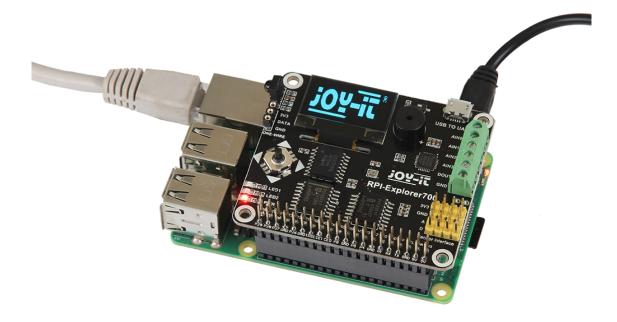
This script shows a text on the display which can be changen in the source code.

sudo python3 image.py

This script displays a picture on the display. This image can also be changed in the code.

sudo python3 animate.py

The last script generates a animation on your OLED.



17. OTHER INFORMATION

Our Information and Take-back Obligations according to the Electrical and Electronic Equipment Act (ElektroG)

Symbol on Electrial and Electronic Products:



This crossed-out bin means that electrical and electronic products do not belong into the household waste. You must hand over your old appliance to a registration place. Before you can hand over the old appliance, you must remove used batteries and replacement batteries which are not enclosed by the device.

Return Options:

As the end user, you can hand over your old appliance (which has essentially the same functions as the new one bought with us) free of charge for disposal with the purchase of a new device.

Small devices, which do not have outer dimensions bigger than 25 cm can be handed in for disposal independently of the purchase of a new product in normal household quantities.

1. Possibility of return at our company location during our opening hours

Simac Electronics Handel GmbH, Pascalstr. 8, D-47506 Neukirchen-Vluyn

2. Possibility of return nearby

We will send you a parcel stamp with which you can send us your old appliance free of charge. For this possibility, please contact us via e-mail at pickup@joy-it.net or via telephone, then please dial 02845 93 60 -23

Information about Package:

Please package your old appliance safe for transport. Should you not have suitable packaging material or you do not want to use your own material, you can contact us and we will send you an appropriate

18. SUPPORT

If any questions remained open or problems may arise after your purchase, we are available by e-mail, telephone and ticket support system to answer these.

E-Mail: service@joy-it.net Ticket-system: http://support.joy-it.net Telephone: +49 (0)2845 98469 – 66 (10 - 17 o'clock)

For further information visit our website: **www.joy-it.net**